## INDIAN INCOME TAX RETURN ACKNOWLEDGEMENT

[Where the data of the Return of Income in Form ITR-1 (SAHAJ), ITR-2, ITR-3, ITR-4, ITR-5, ITR-6,ITR-7 transmitted electronically with digital signature]

Assessment Year 2017-18

	Name									PAN			
	MANI ENCLAVE PRIVATE LIMITED									AAI	ECM1910C		
THE	Flat/Door/Block No				Name Of Premises/Building/Village				F	Form No. which has been electronically transmitted			
N AND	Unit 1A,Juthika Apartment								e				
ATIO TRC ION	Road/Street/Post Office				Area/Locality				tı				
PERSONAL INFORMATION AND THE DATE OF ELECTRONIC TRANSMISSION					11/1, Sunny Park,				5	Status Pvt Company			
L II E O	Town/City/District				State Pin/ZipCode				ode	Aadhaar Number/Enrollment ID			
ERSONAL DATE TR	Kolkata				WEST BENGAL 700019								
P. B.	Designation of AO(Ward/Circle) WA				RD 12(1), KOLKATA				O	Original or Revised ORIGINAL			
	E-fi	lling Acknowledgem	r <b>2</b> ′	275069351311017 Date(I				ate(DE	DD/MM/YYYY) <b>31-10-2017</b>				
ME	1	Gross total income							1	1 5932313			
	2	Deductions under Cha							2	2 25000			
	3	Total Income							3		5907310		
	3a	Current Year loss, if a		and the state of t					3a		0		
COMPUTATION OF INCOME AND TAX THEREON	4	Net tax payable	(1)	Y <sub>N</sub>					4		1764514		
N OF INC THEREON	5	Interest payable		COME TAX DEPARTMEN					5		7349		
N <sub>C</sub> E	6	Total tax and interest							_ 6		1771863		
TAX	7	Taxes Paid	a Advance					100000		_			
MPUTATIO AND TAX			b TDS		7b			1582725 10233		_			
CON			c TCS		_	7c				_			
	d			Assessment Tax		7d	78905		3905				
		e Total Taxes Paid (7a+7b+7c +7d)								7e		1771863	
	8	Tax Payable (6-7e)								8		0	
	9	Refund (7e-6)							9		0		
	10	Exempt Income			Agriculture		0	10		17634			
		. r		Others	ers				17634				

This return has been	digitally signed by	SAMEER VIKRAM AGARWAL	in the capacity of	DIRECTOR
having PAN AD	YPA4896M from I	P Address 122.163.81.4 on 31-10-2017 at 1	KOLKATA	
Dsc Sl No & issuer		de Solutions CA 2014,2.5.4.51=#13133330312c20474e4643204 at,2.5.4.17=#1306333830303534,OU=Certifying Authority,O=G		